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INTEGRATED COST/ SCHEDULE RISK ANALYSIS USING MONTE CARLO SIMULATION OF A CPM MODEL

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Context

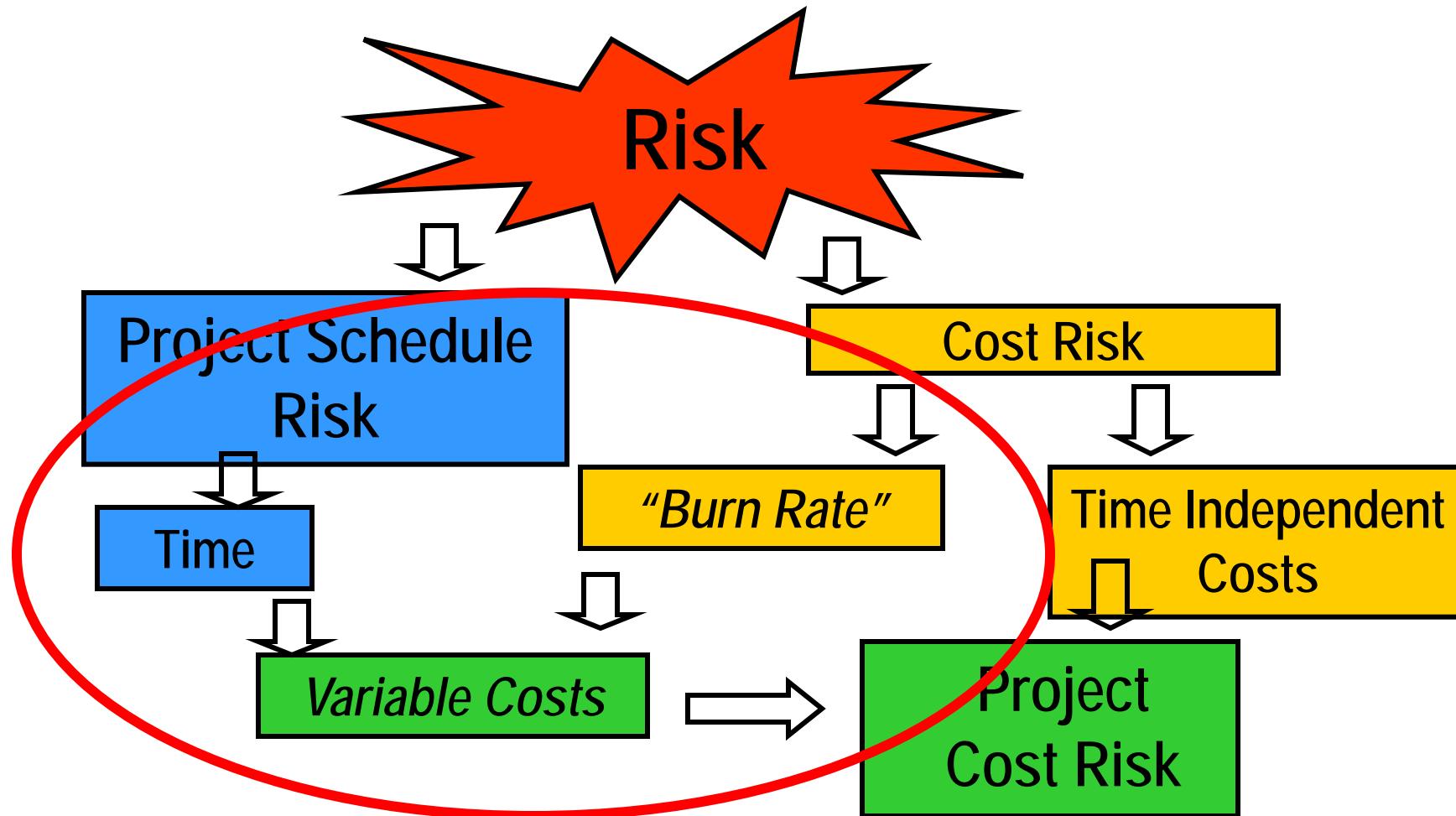
- This presentation will provide up-to-date **integrated project cost and schedule risk analysis using risk drivers**
- The analysis is done in the context of conducting a **Monte Carlo simulation-based schedule risk analysis** of a resource-loaded CPM project schedule
- This presentation illustrates some of the most important features of Risk Drivers used to represent **identified project and systemic risks**
- Modern software that simulates resource-loaded CPM schedules is shown on a **simplified case study**



Components of the MCS Analysis

- The value of integrating project schedule and cost risk in a project schedule is that **different resources are applied**, or the same resources are applied in different mixtures, **to activities that do work**.
- Activities' cost depends on schedule if it is **labor, rented equipment** and the like (**time-dependent**).
 - The cost of these resources may also cost more or less independent of time (their burn rate may vary)
- **Material cost is time-independent**.
 - It may vary but not because of activity duration (total cost may vary)
 - The main importance of this distinction is that **labor and material resources respond differently to schedule uncertainty**.

Cost and Schedule Risk Integration



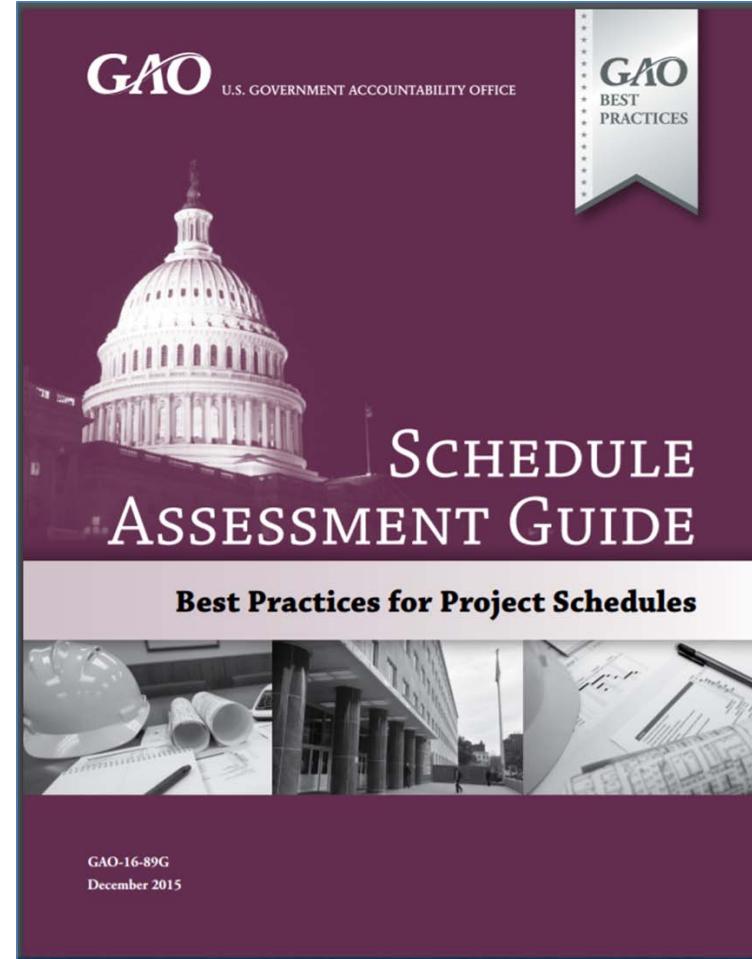
Integration of Cost and Schedule Risk

- Today's computer software simulating project schedules can also **simulate cost associated with the schedule results for each iteration**
 - This method requires **loading** of time-dependent (labor) and time-independent (materials) **resources** on the schedule
 - The MCS results show that a significant fraction of **cost contingency** is **derived indirectly from effect of schedule variation** on cost of project
- Integrating can also provide time and cost scatterplot reveals that the finish date and cost targets needed to achieve a desired **level of confidence in meeting both objectives, the basis of the Joint Confidence Level of NASA**, depends on the degree of time and cost correlation



Good Quality Project CPM Schedule is the Platform for the Analysis

- Critical Path Method (**CPM**) schedule that complies with scheduling best practices.



Good Quality Data about Risks - Workshops

- Often people find that **sharing honestly and openly in a workshop setting is difficult**
 - If there are risks that cannot be discussed because they are unpopular
 - May conflict with management statements or customer requirements
 - Imply the project is in default of the contract terms, or for other reasons
- Groupthink (suppressing dissent)
- The “Moses factor” (i.e. an influential person such as the project manager who overwhelms others)
- Cultural conformity (i.e. decisions that match the organization’s norms).



Good Quality Data about Risks – Confidential Interviews

- Confidential interviews provide the best opportunity for individuals to express their opinions openly, honestly and without fear of retribution
 - These interviews usually identify and calibrate some risks that are not already captured in the risk register, often identifying unknown knowns for the first time.
 - Once the risks are identified in an interview they can be commented on by other interviewees in confidence or brought up anonymously for group buy-in, but nobody knows what anyone else has said in their interviews



Benchmarking Results with Actual Data

- Review of **existing data on comparable and recent projects** should also be brought to the risk data collection exercise
 - Comparing the data and results for the current project with past experience represented by completed projects may bring what is called the **“outside view” to the discussion**
- Making reference to **historic databases can often bring more realism** to the risk discussion
 - Provide a means to **corroborate identified risks with their likelihood and uncertainty ranges**

Uncertainty is Background Noise 100% Likely

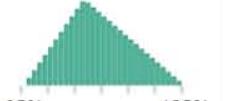
Project Risks				
Name	Description	Risk Type	Probability	Color
Risk- 4	Engineering Risk	Standard	30%	
Risk-1	Project C&S Uncertainty	Standard	100%	
Risk-2	Fabrication Risk	Standard	55%	
Risk-3	Installation Risk	Standard	60%	
Risk-5	Procurement Risk	Standard	20%	
Risk-6	HUC Risk	Standard	70%	
Risk-7	Systemic Team Risk	Standard	30%	
Risk-8	Labor Cost Risk	Standard	75%	

Impacts of Risk-1

Impact activities independently

Pre-Mitigated Position

Schedule Impact

Type: Relative Distribution: Triangle Min: 85% Likely: 100% Max: 125% 

Cost Impact

Type: Relative Distribution: Triangle Min: 85% Likely: 100% Max: 120% 



Risk Drivers Represent Identified Project-Specific and Systemic Risks

- Risk Drivers are identified “root cause risks” with:
 - Probability of occurring on the project (% of iterations occurring)
 - Impact on activity durations if they do occur, expressed as probability distributions of multiplicative factors

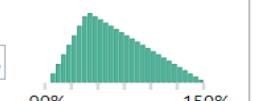
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Risk- 4	Engineering Risk	Standard	30%	
Risk-1	Project C&S Uncertainty	Standard	100%	
Risk-2	Fabrication Risk	Standard	55%	
Risk-3	Installation Risk	Standard	60%	
Risk-5	Procurement Risk	Standard	20%	
Risk-6	HUC Risk	Standard	70%	
Risk-7	Systemic Team Risk	Standard	30%	
Risk-8	Labor Cost Risk	Standard	75%	

Impacts of Risk-2

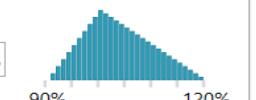
Impact activities independently

Pre-Mitigated Position

Schedule Impact

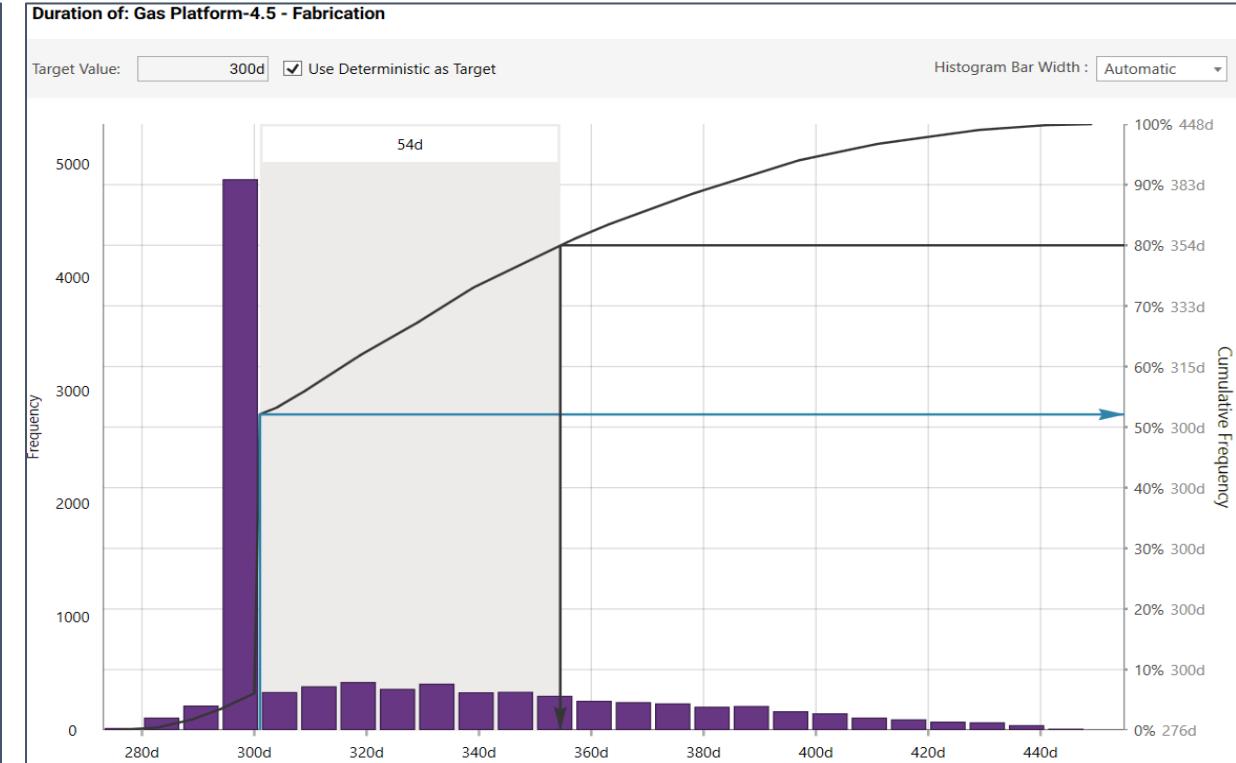
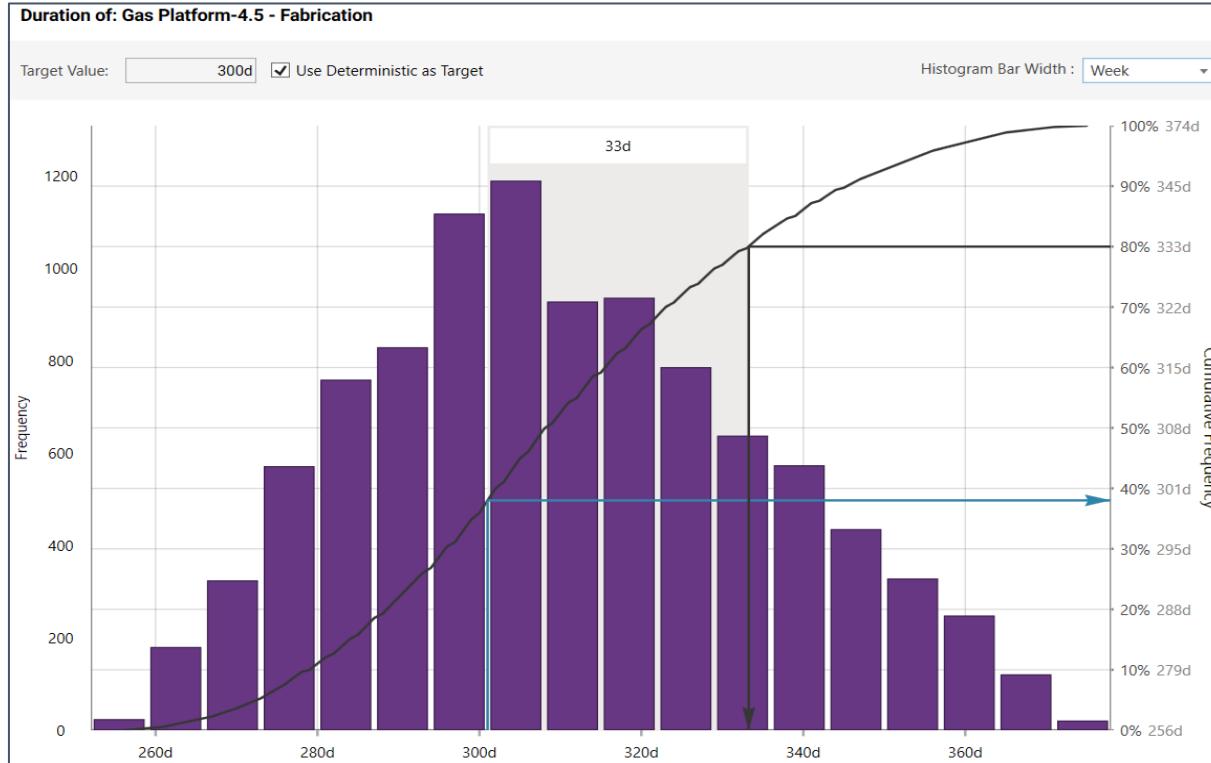
Type: Relative Distribution: Triangle Min: 90% Likely: 105% Max: 150% 

Cost Impact

Type: Relative Distribution: Triangle Min: 90% Likely: 100% Max: 120% 



Uncertainty and Risk Drivers' Impact on Activity Durations during Monte Carlo



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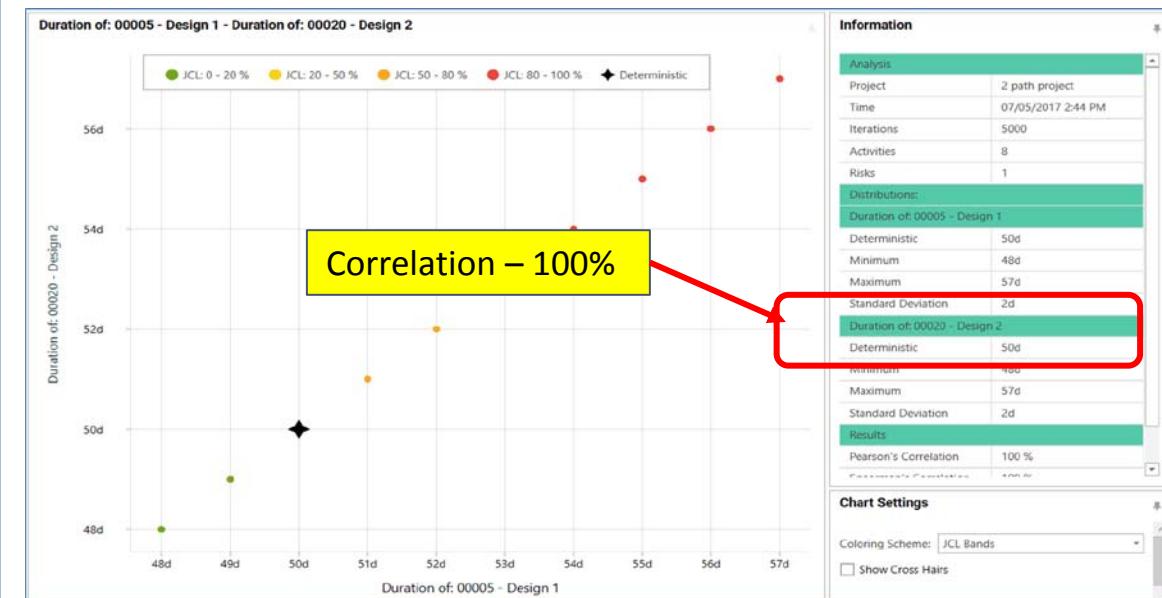
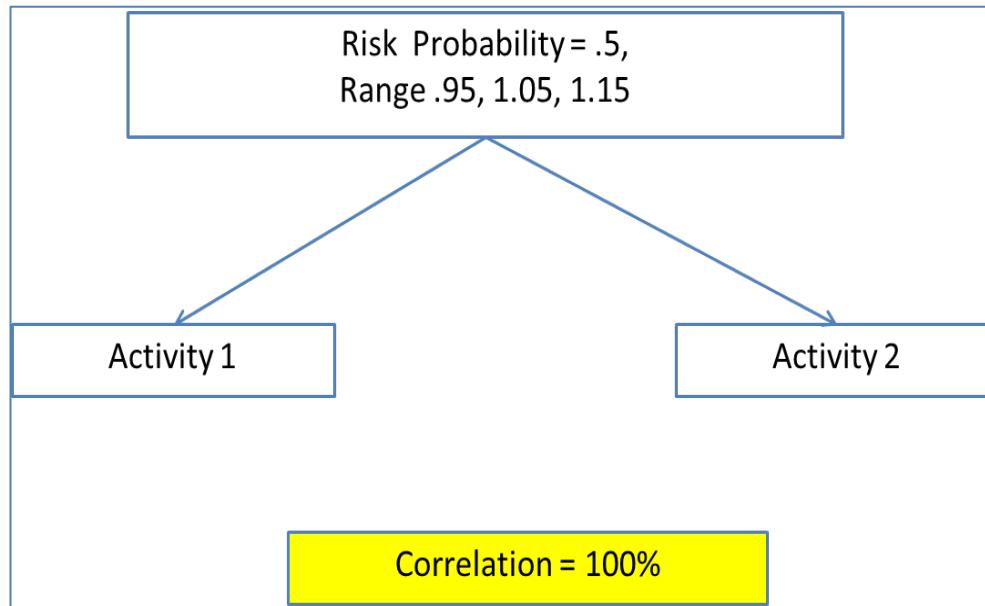
Assigning Risks to Multiple Activities

		Risk- 4	Risk-1	Risk-2	Risk-3	Risk-5	Risk-6	Risk-7
Id		Description						
▲	Gas Platform-4	Offshore Gas Production Platform	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
▷	Gas Platform-4.1	Milestones and Hammocks	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
▷	Gas Platform-4.2	Decision Making	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
▷	Gas Platform-4.3	Engineering	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
▷	Gas Platform-4.4	Procurement	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
▷	Gas Platform-4.5	Fabrication	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
	E1000	Fabricate Drilling Topsides	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
	E1020	Fabricate CPP Topsides	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
	E1030	Fabricate CPP Jacket	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
	E1010	Fabricate Drilling Jacket	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
▷	Gas Platform-4.6	Drilling	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
▷	Gas Platform-4.7	Installation	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>
▷	Gas Platform-4.8	HUC	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>

Using Multiplicative Impact Factors with Risk Drivers Helps to allocate risks to long and short activities alike

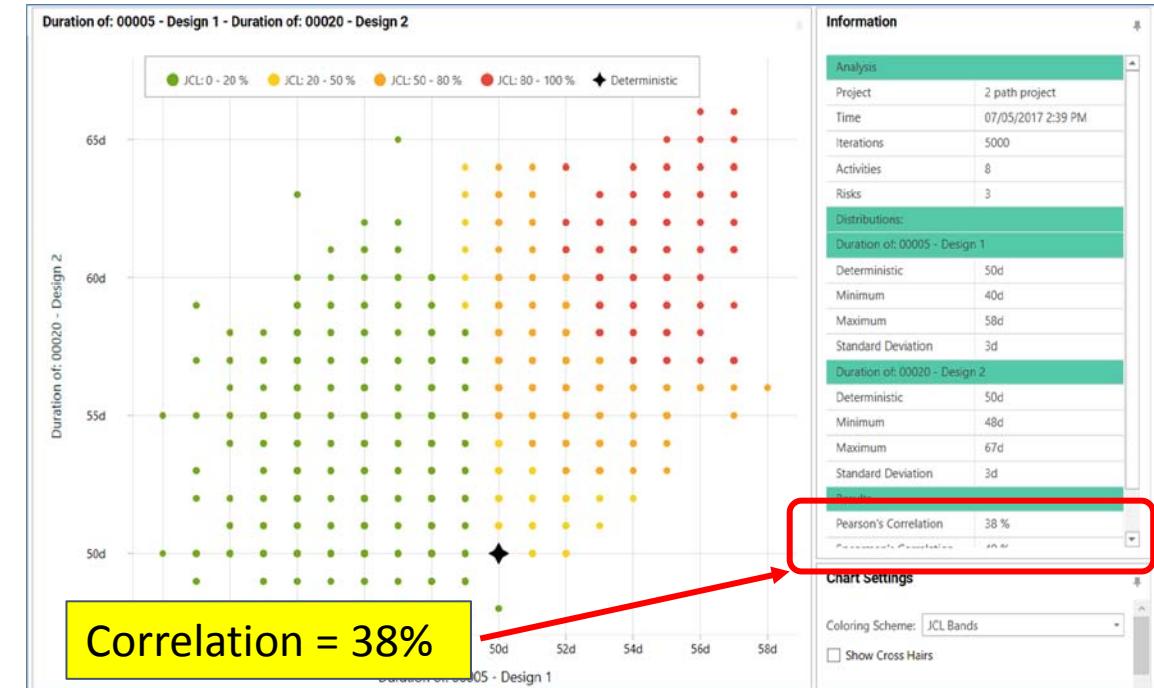
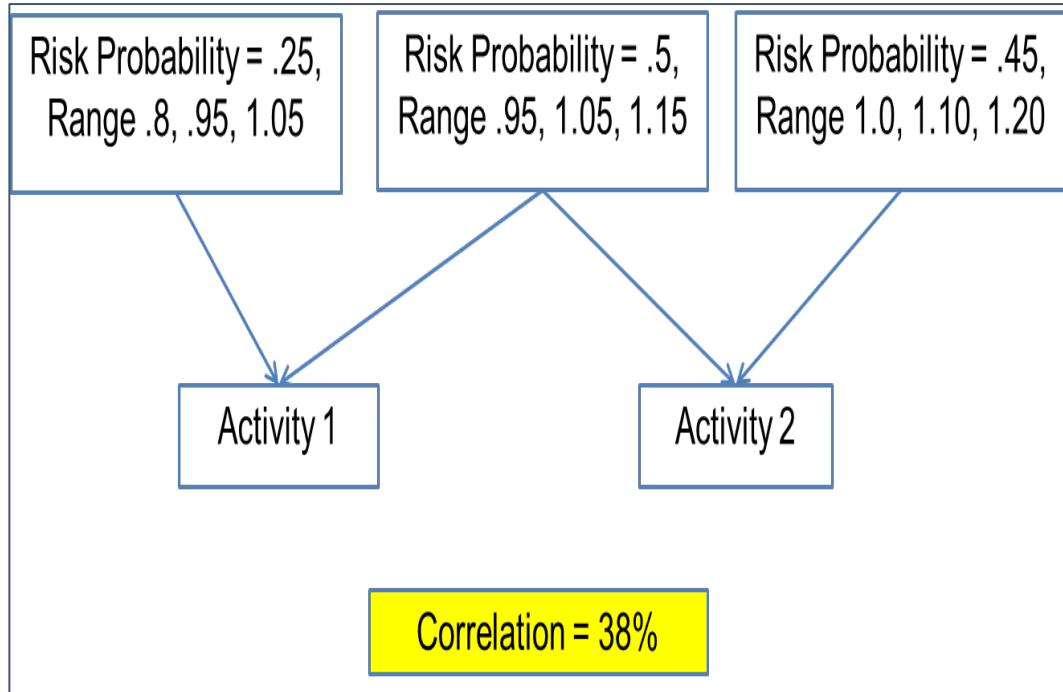


Risk Drivers cause Correlation during Simulation



Correlation between activity durations is an important component of any schedule risk analysis
Correlation is caused by one risk affecting multiple activities

Correlation Depends on Which Risks Affect Durations



With one risk common to two activities but others affecting only one but not the other activity, the correlation declines - to 38% in this example
We are particularly inaccurate in estimating (“guessing”) correlation coefficients. It is good to model during simulation

Risks can be Modeled in Parallel or in Series

- Earlier the risks would all build on each other if they occurred on the same activity on the same Monte Carlo iteration
- Originally the multiplicative factor on an activity's duration was the multiplicative product of all risks' occurring in that iteration. This caused some activities' durations to be unreasonably long
- Now, modeling risks in parallel if they can be recovered from simultaneously allows the model to select the largest multiplier occurring in an iteration, assuming the other risks can be addressed simultaneously



Risks can be Modeled in Parallel or in Series

If these two risks cannot be recovered from simultaneously they are entered *in series*

Risk 1: 1.2 factor

Risk 2: 1.25 factor

Use $(1.2 \times 1.25 = 1.5)$ multiplicative factor for this iteration

If these two risks can be recovered from simultaneously they are entered *in parallel*

Risk 1: 1.2 factor

Risk 2: 1.25 factor

Use 1.25 (Largest) multiplicative factor for this iteration



Risk Prioritization for Focused Risk Mitigation

- Earlier the sensitivity measures for prioritizing risks showed tornado diagrams based on the correlation of the activity with total project duration
- Then tornado diagrams could show correlation of the identified risk with total project duration, but still based on correlation between the risk and total project duration
- Now we prioritize risks by a successive simulation method that shows risks prioritized by the number of “days saved if the risk were mitigated”
 - This measure is useful for management.
 - Answers the question: “If we spend \$5 million how many days do we save”

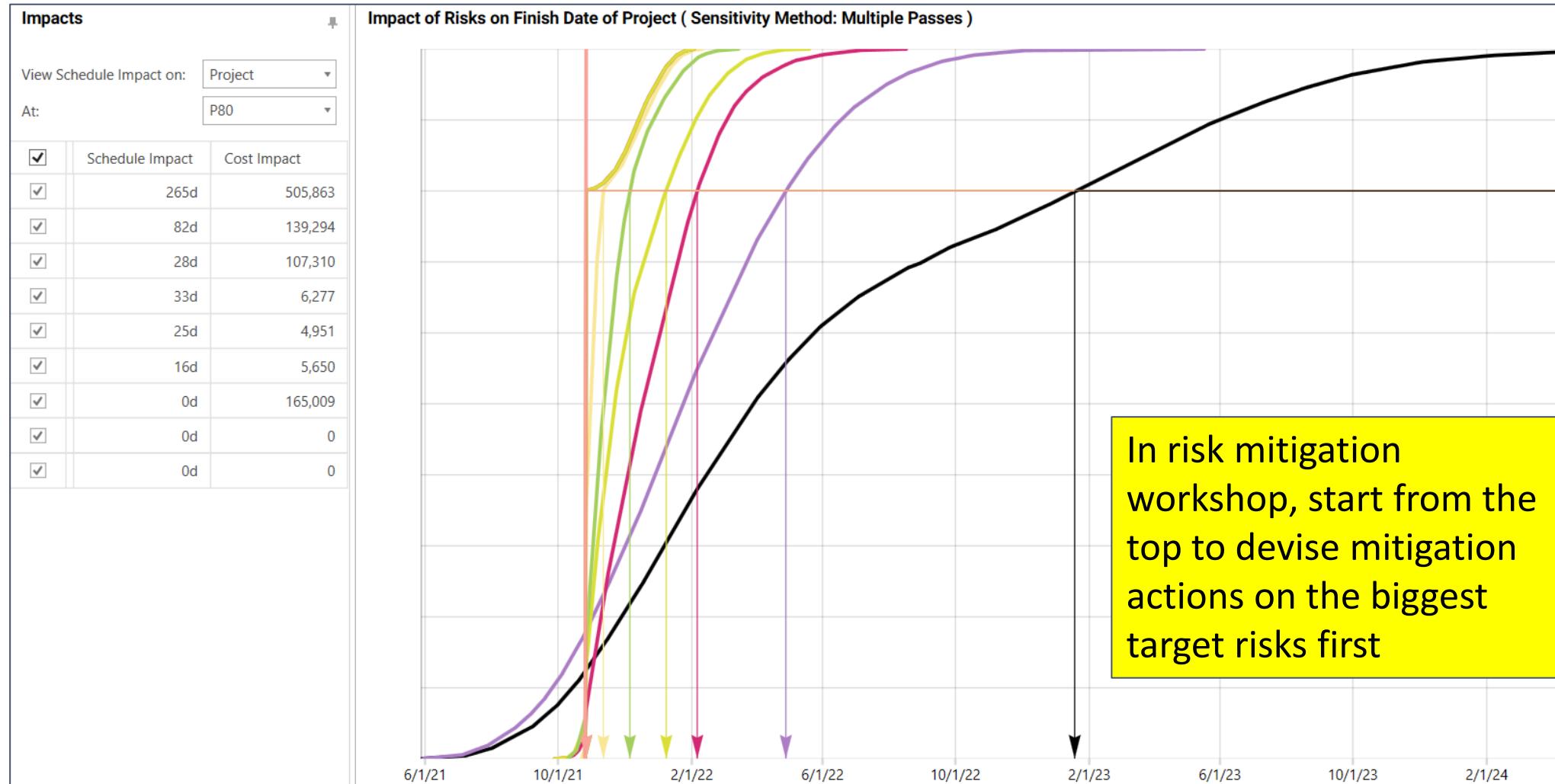


Strategy for Risk Prioritization using Simulations

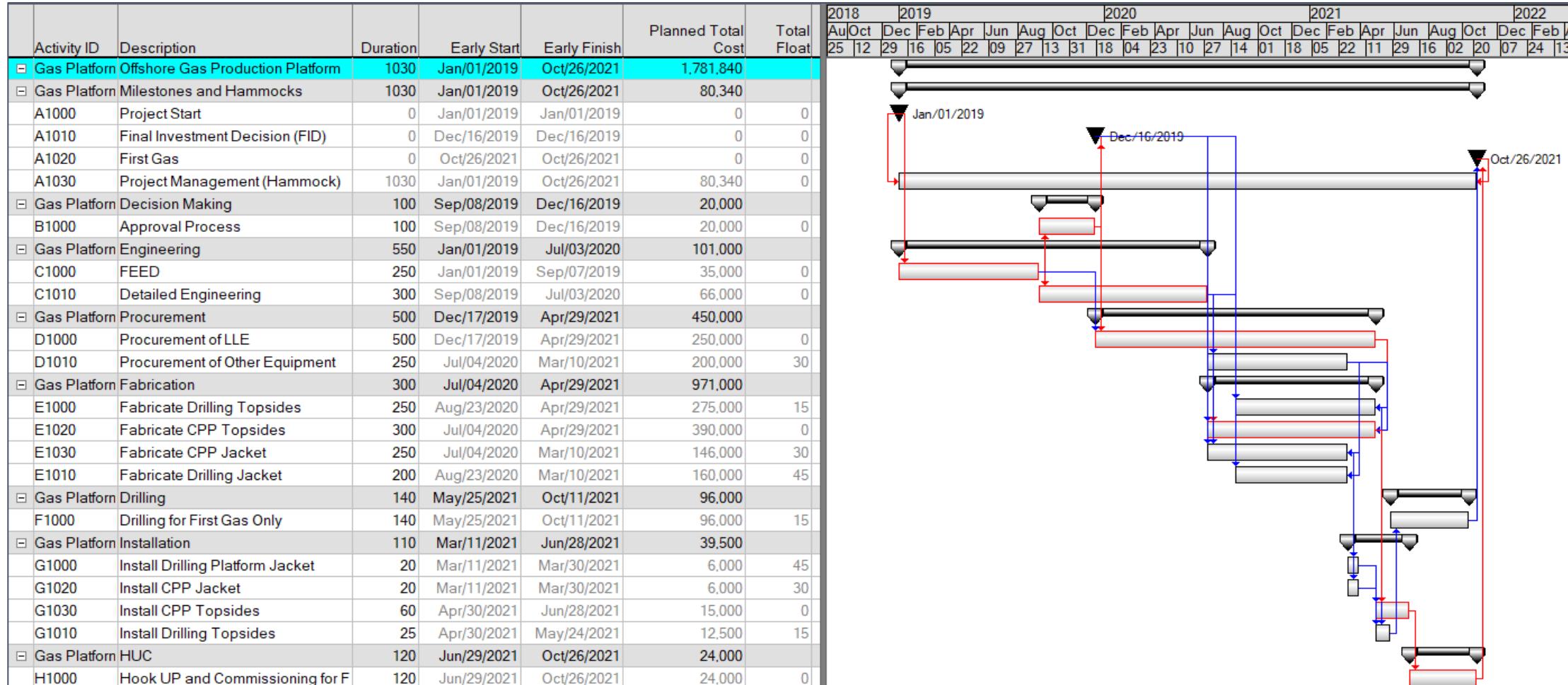
Iterative Approach to Prioritizing Risks (Based on Days Saved if Fully Mitigated at P-80)								
Risk #	1	2	3	4	5	6	7	8
Priority Level	Uncertainty	Fabrication	Installation	Engineering	Procurement	HUC	Systemic Team	Labor Cost
1	X	X	X	X	X	X	1	X
2	2	X	X	X	X	X		X
3		3	X	X	X	X		X
4			X	4	X	X		X
5			X		X	5		X
6			X		6			X
7			7					X
8								8

Identify the risk that provides the greatest number of days if fully mitigated (“disabled”). Remove, repeat the process with remaining risks, repeat until all risks have been chosen in priority order

Successive Elimination of Risks in Priority Order



Case Study to Illustrate Risk Drivers on Project

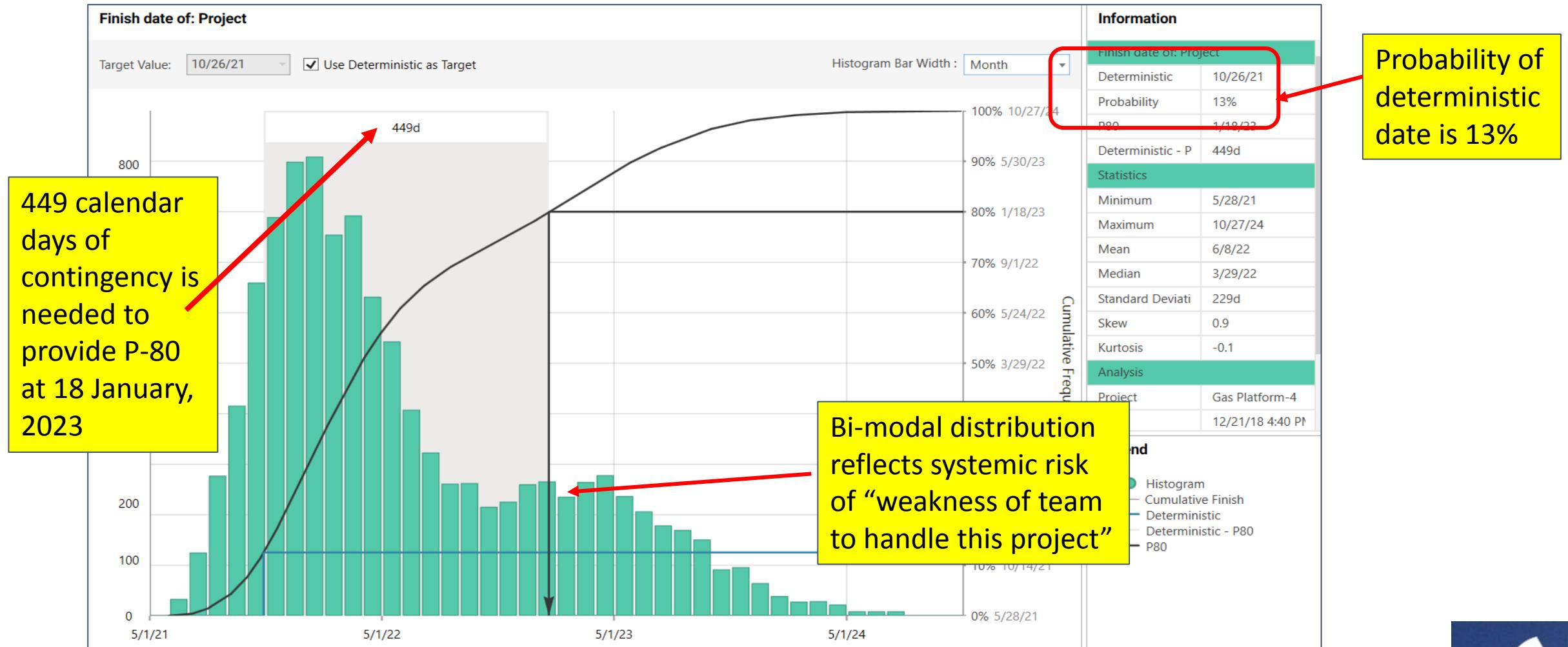


Results for Schedule and Cost Targets

- The organization sets its own targets for cost and schedule success
- Often clients use the 80th percentile, “P-80,” to provide a cushion for risks not yet identified
- P-80 means that there is an 80% chance, given the schedule and risks, that the project will finish on that date or earlier, at that cost or less
 - The P-80 for schedule represents uncertainty and risk drivers plus the logic of the schedule
 - The P-80 for cost represents the indirect effect of schedule risk on cost as well as the uncertainty and risk drivers affecting cost items, such as price of steel, suppliers being busy



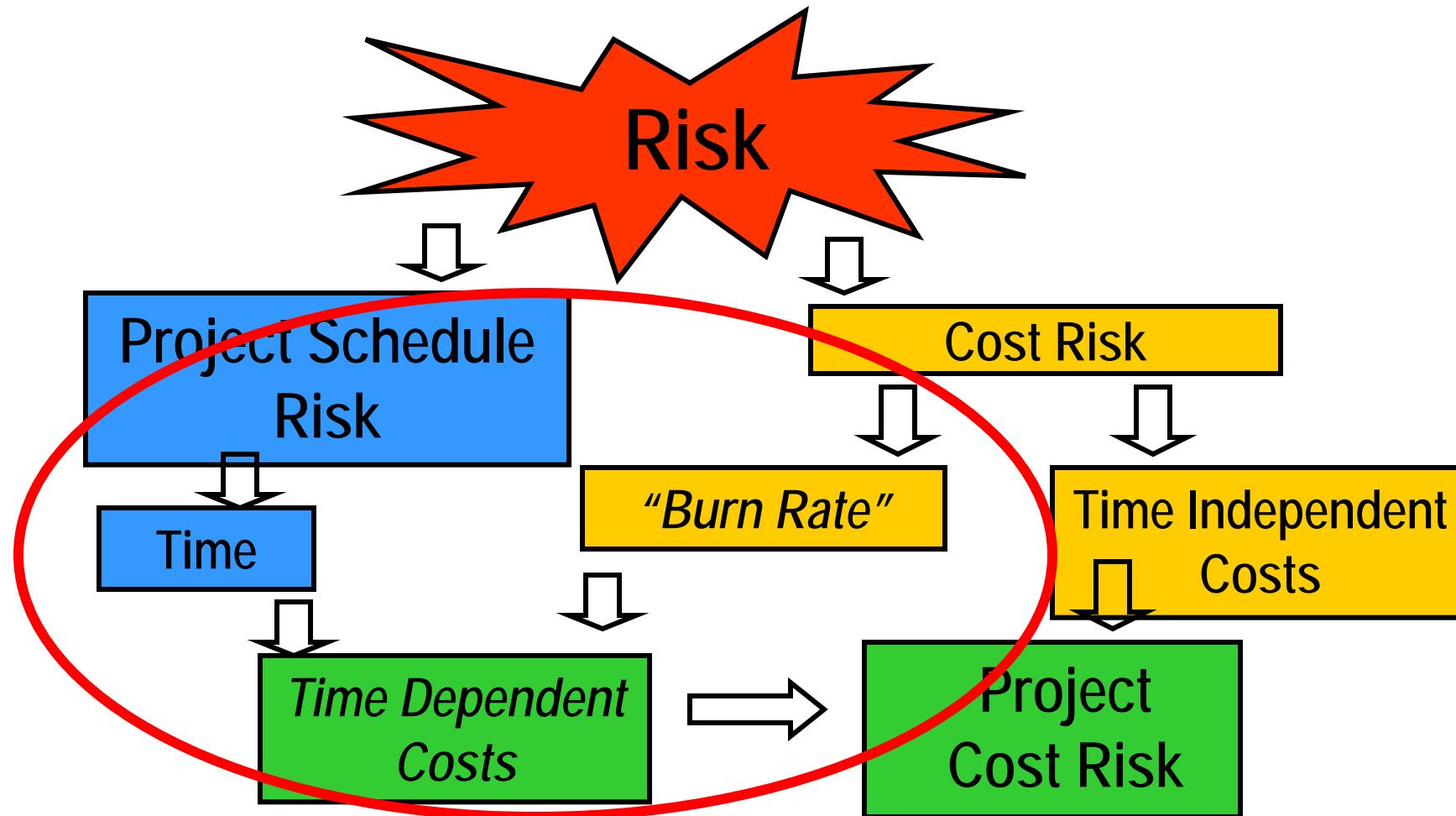
Example of P-80 Schedule Results



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Cost and Schedule Risk Integration

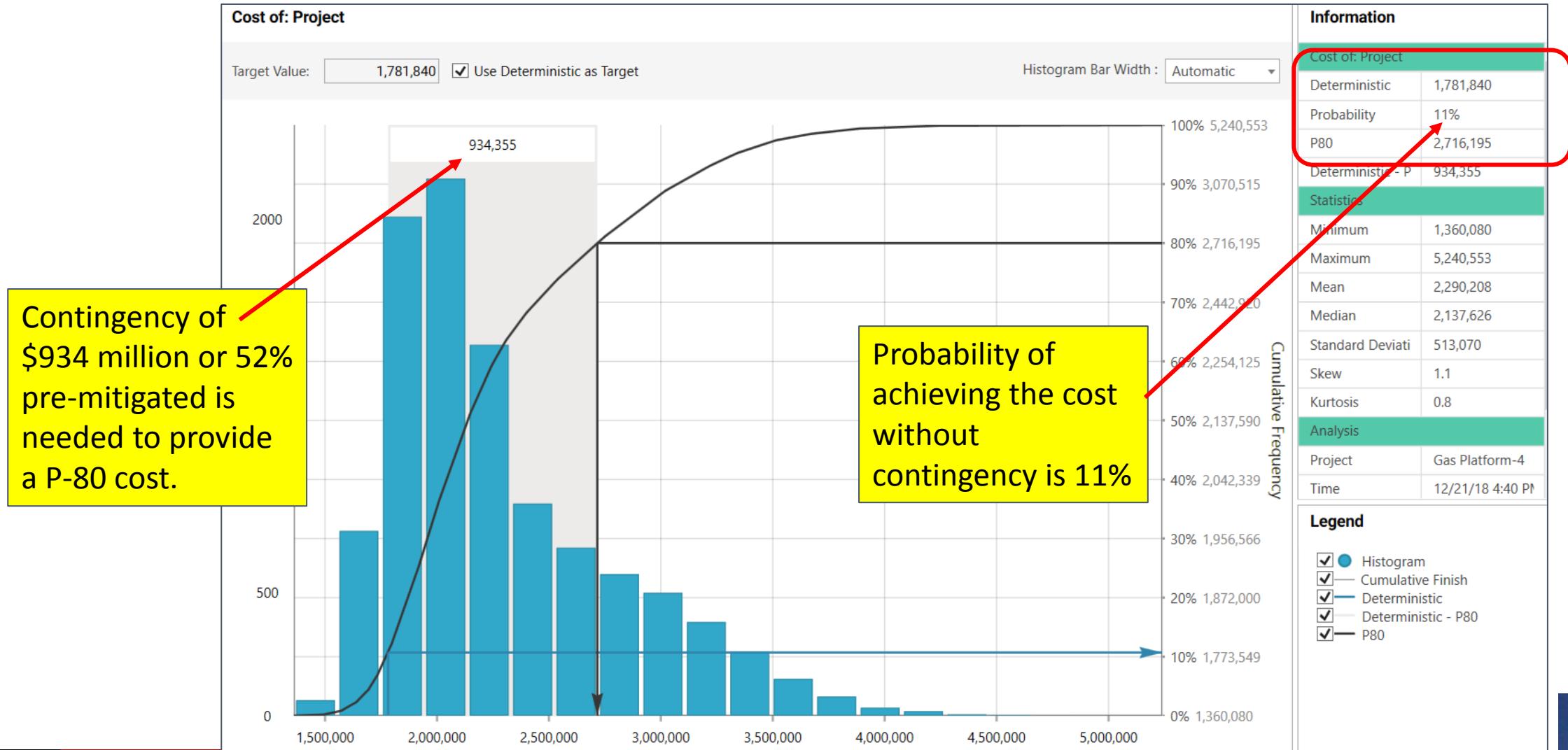


Representing the Risk to Both Cost and Schedule – The Joint Confidence Level (JCL)

- Schedule is loaded with costs as Time-Dependent and Time-Independent resources
- Time dependent resources are labor and rented equipment that cost more if the activities (including indirect cost hammocks) take longer
 - With some cost-type risks e.g., labor market drives labor rates, labor cost can vary even if the schedule is perfect
- Time-independent resources are materials and equipment for installation.
 - They may cost more or less than estimated but not because of time
- This analysis does not say who pays. It is not an analysis of contracts or an assessment of whether fixed price contracts successfully transfer the risk to contractors from owners



Example of P-80 Cost Risk Results

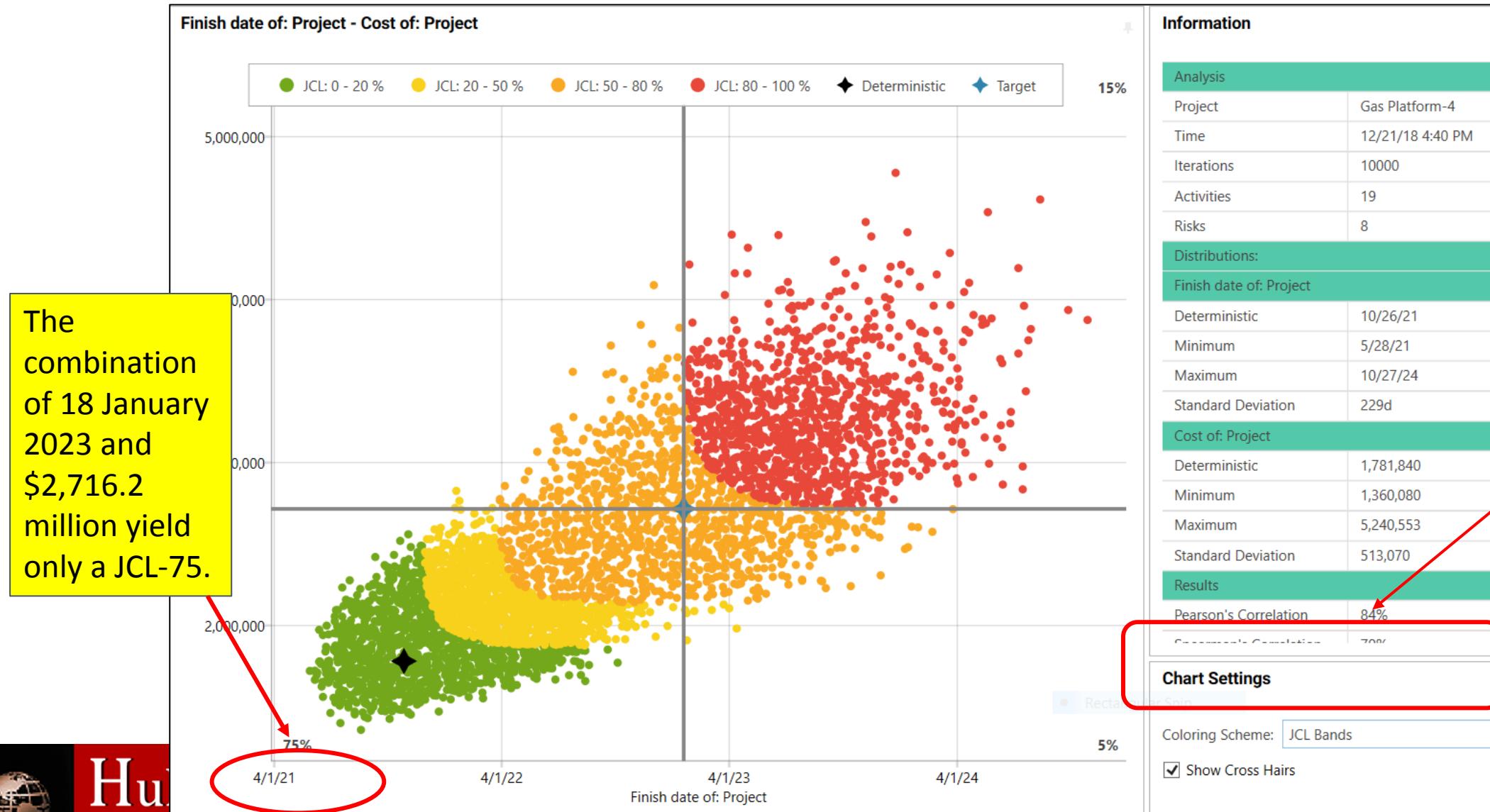


A New Concept – the Joint Confidence Level

- Joint (cost and schedule) Confidence Level (“JCL”) is just NASA’s name for integrated cost-schedule risk analysis
- The JCL highlights the fact that cost and schedule are not perfectly linked (their correlation is < 100%) so using the P-80 values for schedule and cost will not ensure meeting those two targets together
- Additional time and money will be needed above the P-80 values of 18 January 2023 and \$2,716.2 million if BOTH COST AND SCHEDULE ARE TO BE MET TOGETHER
- The JCL is based on matching the P-80 (NASA uses P-70) joint probability of cost and schedule with the cost-finish date scatter diagram to find the most likely combination of cost and finish date to achieve 80% (JCL-80) confidence



P-80 Cost and Schedule do Not Make JCL-80



The combination of 18 January 2023 and \$2,716.2 million yield only a JCL-75.

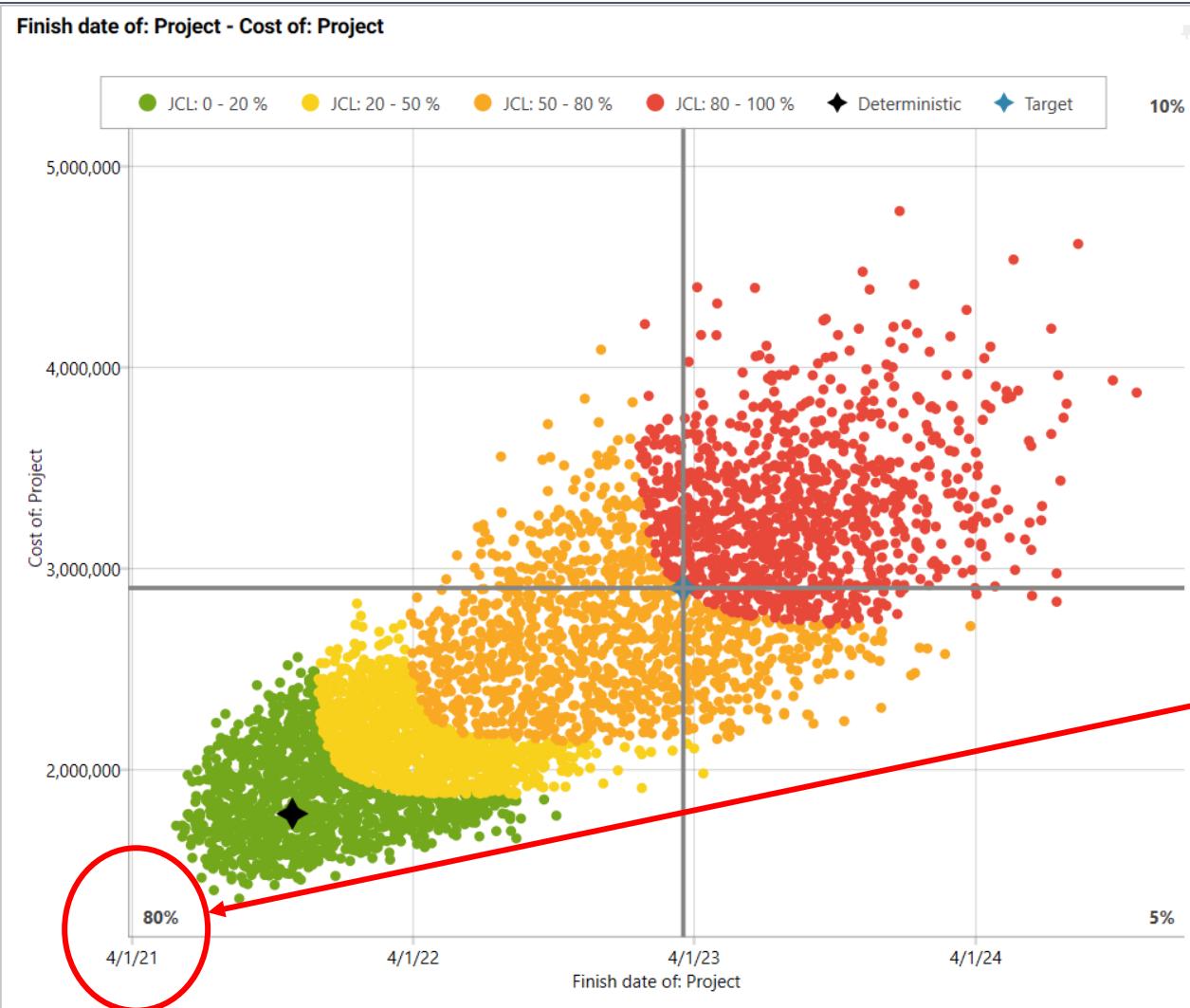
In this case total project cost and finish date are correlated 84%



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How Much Time and Budget are needed for JCL-80?



One possible JCL-80 combination that looks like it lies in the “sweet spot” of the scatter diagram would require:

- A finish date of 3/18/2023 or an additional 2 months from the P-80 schedule result
- A budget of \$2,903.9 million or \$187.7 million more than the P-80 cost result

This result is more achievable than the P-80 values



What is the benefit of JCL-80 over P-80?

- There is some evidence, presented at the 2018 NASA Cost and Schedule Symposium, that NASA is having better success achieving the cost and schedule targets provided to Congress after implementing the Joint Confidence Level
- This is not because they are suddenly better project managers at NASA, but they are better “project prognosticators” and more able to make more realistic targets using JCL than P-values





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